

Editor: _____	Date: _____
Company: _____	Contact Person: _____
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Town: _____	Telefax: _____
Web: _____	E-Mail: _____
Quantity: _____	Time schedule: _____
Project: _____	Project no.: _____

1. Application and work cycle

Type of application		
Static load (e.g. vertical axis)		
End position monitoring by drive unit		
Acceleration time (ta)		
Constant travel time (tc)		
Delay Time (td)		
Break time (tp)		

2. Requirements for the motor

Maximum load including acceleration		Nm (N)
Maximum load without any acceleration		Nm (N)
Maximum speed (velocity)		U/min (m/s)
Maximum acceleration		U/min/s (m/s²)
Holding break		
Motor shaft design		
Rotative feedback system		
Accuracy of the rotary feedback system		
Linear feedback system		
Accuracy of the linear feedback system		mm
Resolution of the linear feedback system (optional)		mm
Connection cables motor to controller		
Cable length		m

3. Requirements for the drive

Supply voltage		VAC
Netfilter		
Braking resistor		
Bus interface to the higher-level controller		
Safety-functions (STO SIL2, STO SIL3, SS1, SS2, SOS, SSR, SLS, SDI, SBC, SLI, SLP)		

4. Description of the application / other / special features
